

Electromagnetic surveying

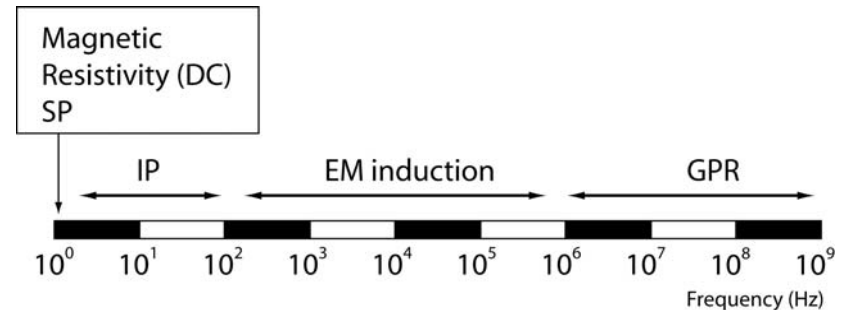
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Introduction

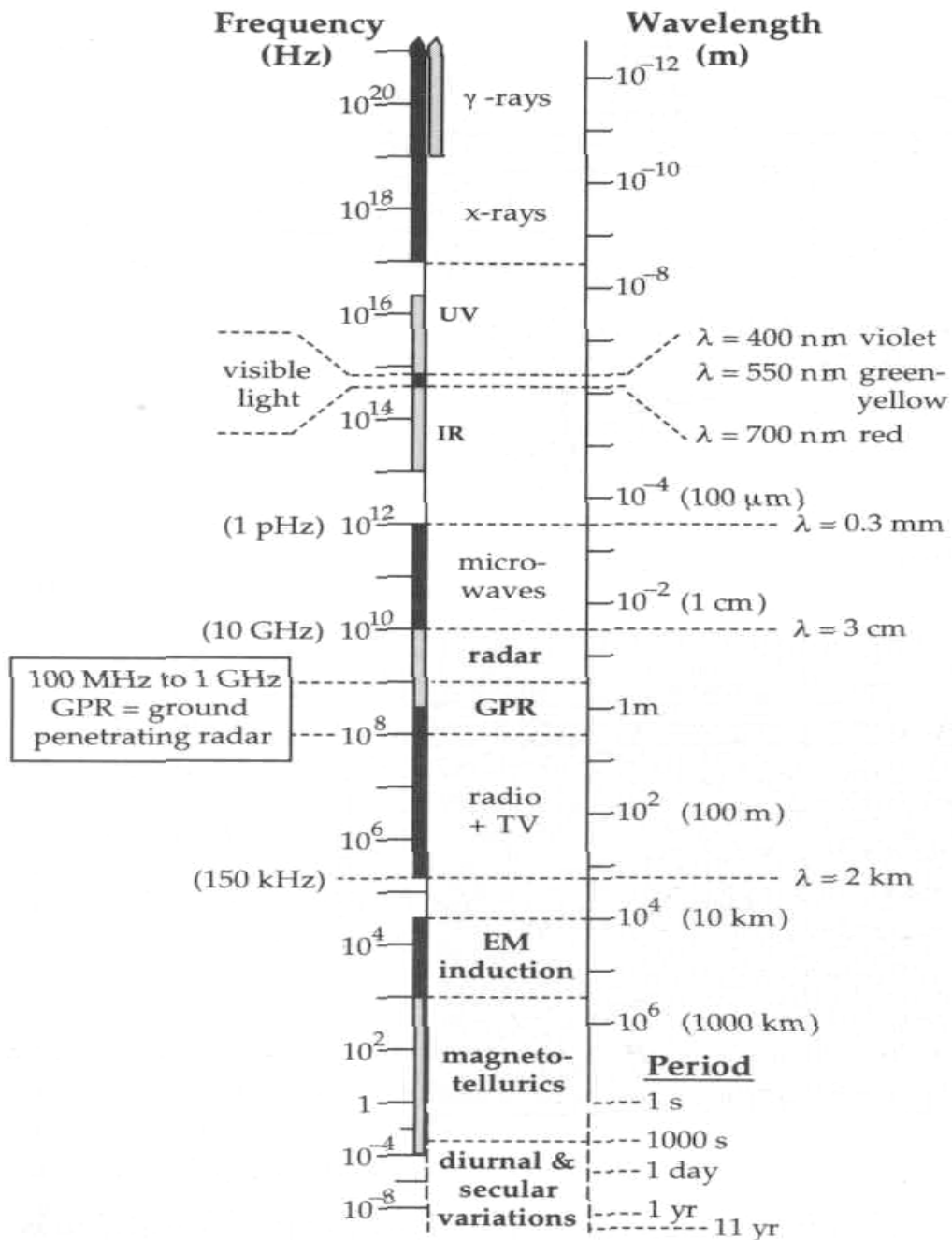
Electrical surveying...

- Resistivity method
- Induced polarization method (IP)
- Self-potential (SP) method



Higher frequency methods (electromagnetic surveys):

- Electromagnetic induction methods
- Ground penetrating radar (GPR)



Electromagnetic method

Electromagnetic (EM) surveying methods make use of the response of the ground to the **propagation of electromagnetic field**. This response vary according to the **conductivity** of the ground (in S/m).

- Primary EM fields are generated using a alternating current in a loop wire (coil) or a natural EM source
- The response of the ground is the generation of a secondary EM field
- The resultant field is detected by the alternating currents that they induce in a receiver coil

Application

- Exploration of metalliferous mineral deposits
- Exploration for fossil fuels (oil, gas, coal)
- Engineering/construction site investigation
- Glaciology, permafrost
- Geology
- Archaeological investigations

Structure of the lecture

1. Equations in electromagnetic surveying
2. Survey strategies and interpretation
3. Conclusions



1. Equations in electromagnetic surveying

Maxwell equations

$$\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0 \quad \text{Faraday induction}$$

$$\nabla \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{j} \quad \text{Ampère – Maxwell}$$

$$\nabla \cdot \vec{D} = p \quad \text{or} \quad \nabla \cdot \vec{j} = \frac{\partial p}{\partial t}$$

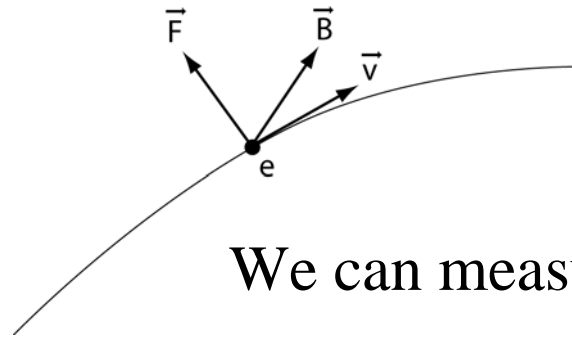
$$\nabla \cdot \vec{B} = 0$$

\vec{E}	electrical field	(V/m)
\vec{B}	magnetic induction field	(Vs/m ²)
\vec{H}	magnetic field strenght	(A/m)
\vec{D}	displacement field	(C/m ²)
\vec{j}	current density	(A/m ²)
p	charge density	(C/m ³)

B and H fields

$$\vec{F} = e\vec{v} \times \vec{B}$$

$$\vec{H} = \frac{\vec{B}}{\mu_0 \mu}$$



We can measure B , not H !

Example of values for μ :

Hematite, quartz: $\mu \cong 1$

Magnetite: $\mu \cong 5$

$\mu_0 = 4\pi 10^{-7} \left(\frac{\text{Vs}}{\text{Am}} \right)$ permeability for vacuum

μ permeability of material

\vec{B} magnetic induction field (Vs/m^2)

\vec{H} magnetic field strenght (A/m)

Frequencies

$$\omega = 2\pi f = 2\pi \frac{1}{T}$$

f frequency (Hz)

T period (s)

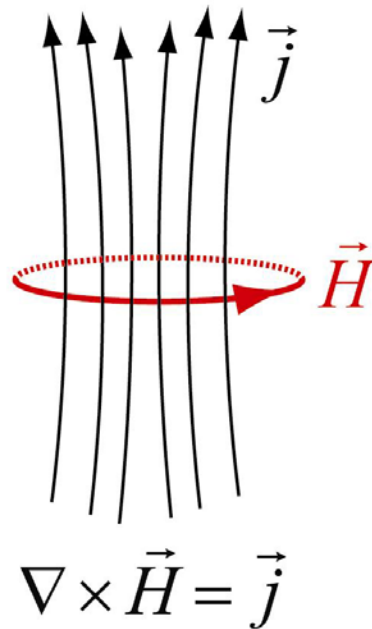
ω angular velocity (rad/s)

In the field, some frequencies are considered as noise and must be filtered out:

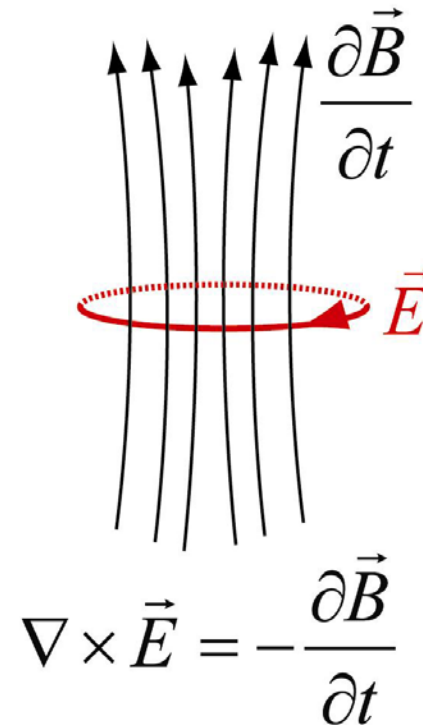
- Light 50 Hz
- CFF/SBB 16.6 Hz
- 3rd harmonic 150 Hz

Basic theory: induction EM

Ampère



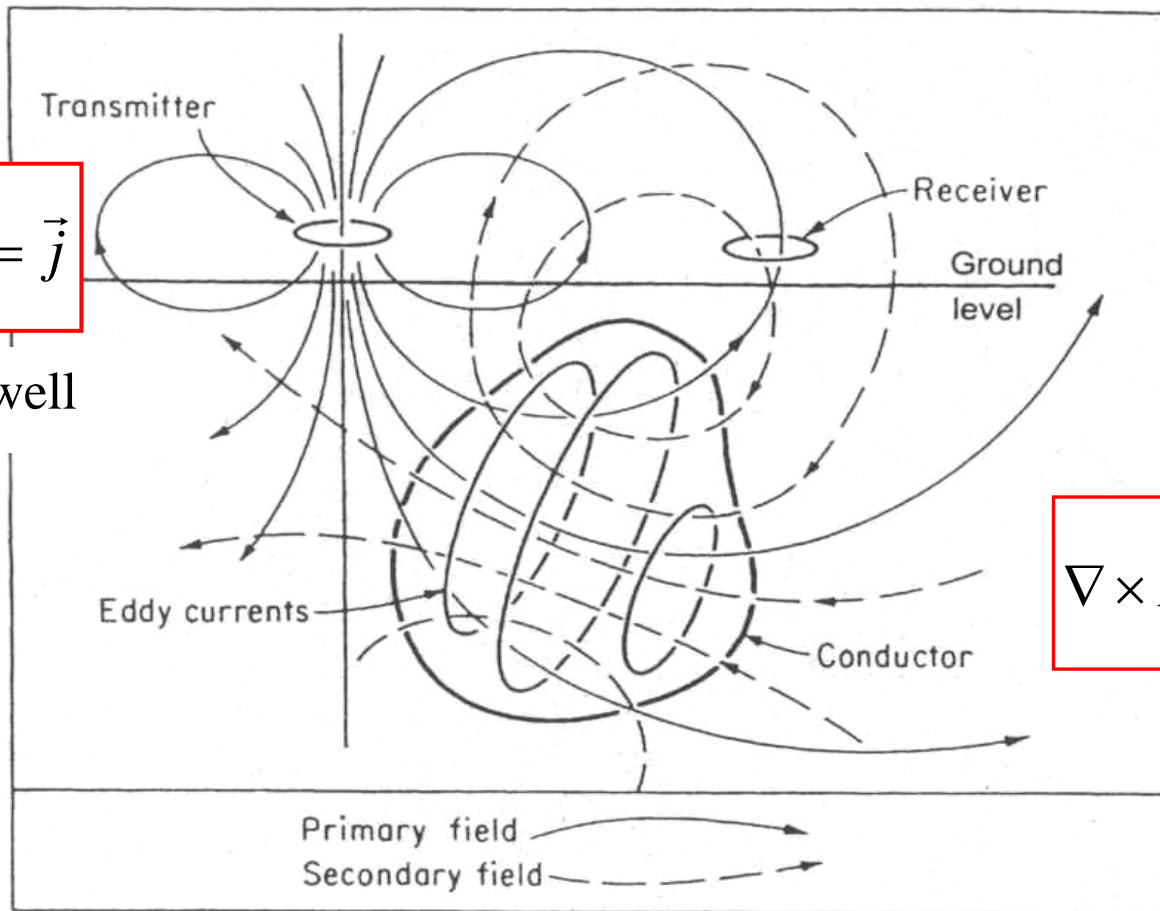
Faraday



Basic theory: induction EM

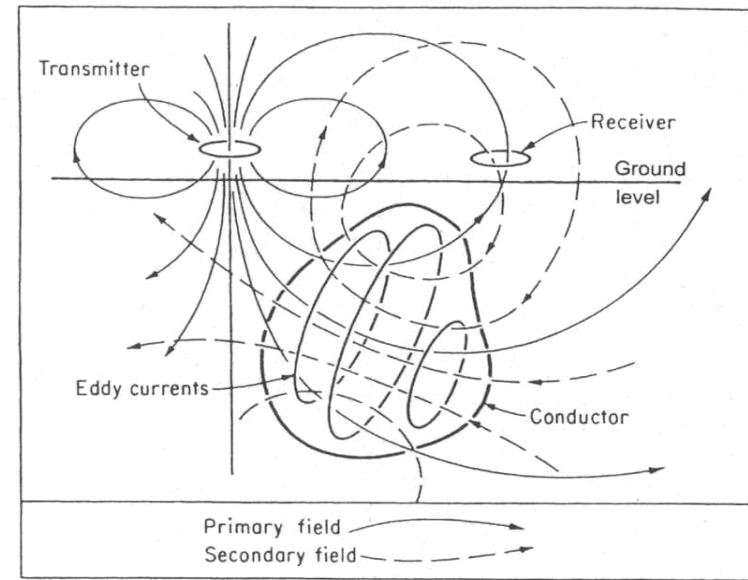
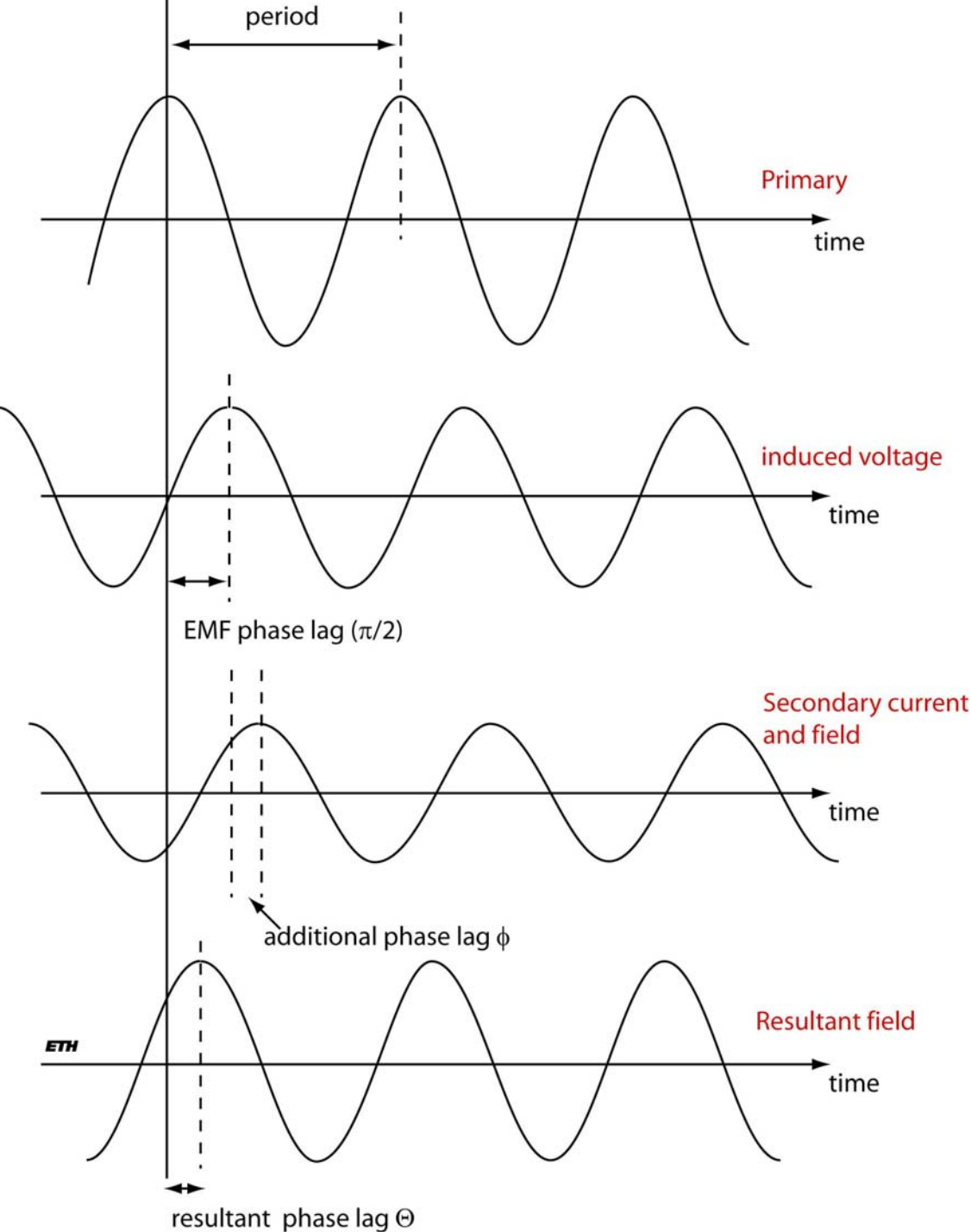
$$\nabla \times \vec{H} - \frac{\partial \vec{D}}{\partial t} = \vec{j}$$

Ampère-Maxwell



$$\nabla \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

Faraday

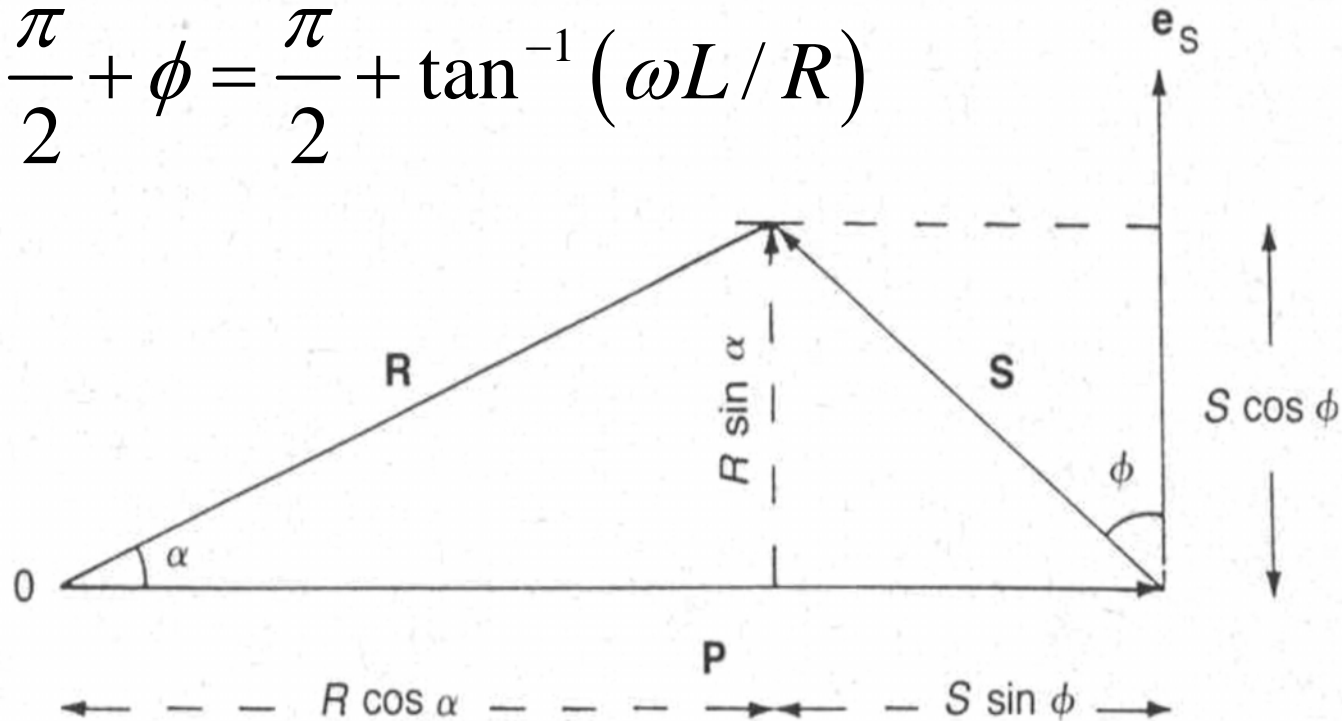


$$\Theta = \frac{\pi}{2} + \phi = \frac{\pi}{2} + \tan^{-1}(\omega L / R)$$

R is the resistance of the conductor
 L is the inductance of the conductor
 (or its tendency to oppose a change in the applied field)

Real and imaginary components

$$\Theta = \frac{\pi}{2} + \phi = \frac{\pi}{2} + \tan^{-1}(\omega L / R)$$



$S \sin \phi$

in-phase component (real)

$S \cos \phi$

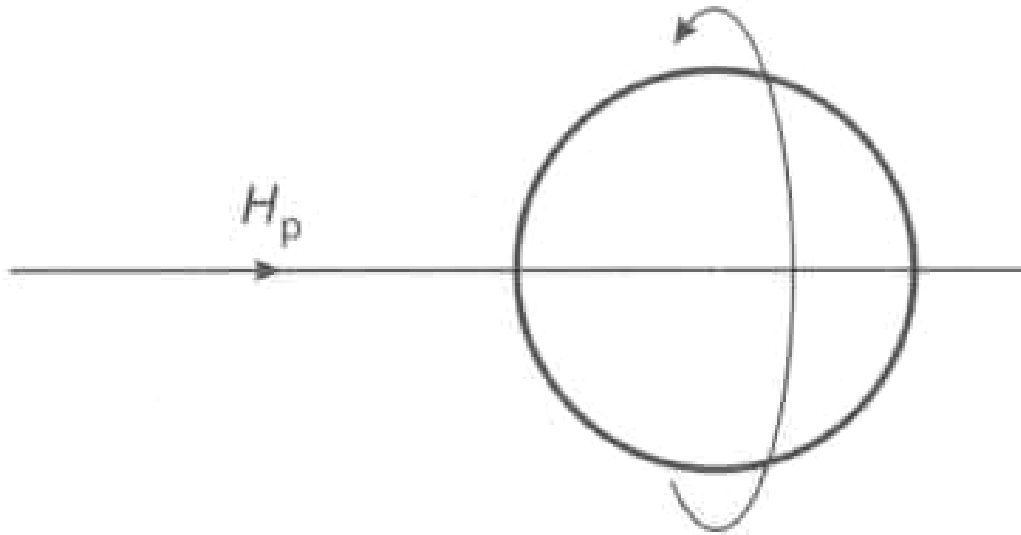
out-of-phase component (imaginary)

Effect of a conductive body

$$\Theta = \frac{\pi}{2} + \phi = \frac{\pi}{2} + \tan^{-1}(\omega L / R)$$

- Large conductivity ($R \rightarrow 0$ and $\phi \rightarrow \pi/2$): $\Theta \rightarrow \pi$
- Low conductivity ($R \rightarrow \infty$ and $\phi \rightarrow 0$): $\Theta \rightarrow \pi/2$

Tilt-angle methods



The receiving coil is turned until a null position is reached (no-signal): the plane of the coil then lies in the direction of the arriving field

Depth of penetration and skin depth

Skin depth: depth δ at which the amplitude of the field reaches $1/e$ of its original value at the source

$$\delta = \sqrt{\frac{2\rho}{\mu_0\omega}} \approx 503 \sqrt{\frac{\rho}{f}}$$

Depth of penetration: maximum depth z_e at which a conductor may still produce a recognizable EM anomaly (empirical relation)

$$z_e \approx \frac{100}{\sqrt{\sigma f}}$$



2. Survey strategies and interpretation

Classification of EM methods

Uniform field methods

- Magnetotelluric (MT)
- Audio-magnetotelluric (AMT)
- Very-Low Frequency (VLF-tilt, VLF-R)
- Controlled source audio-magnetotelluric (CSAMT)

Dipolar field methods

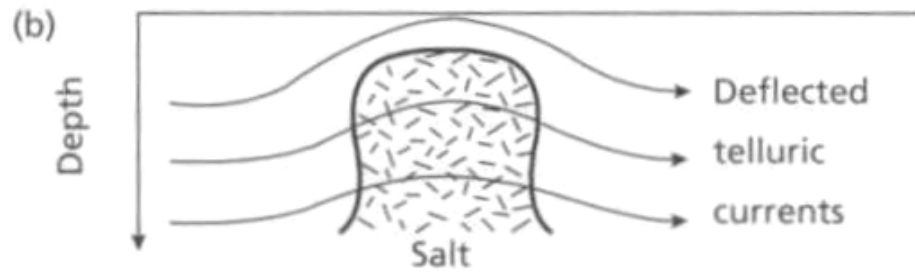
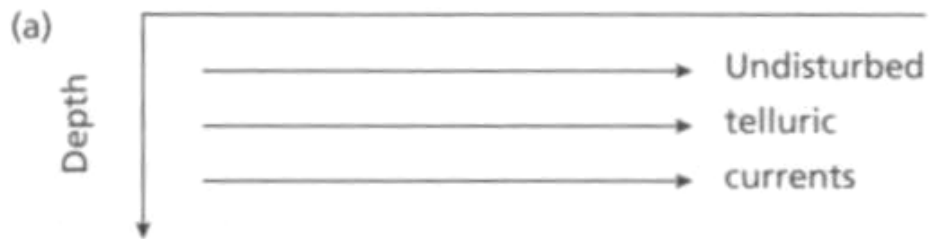
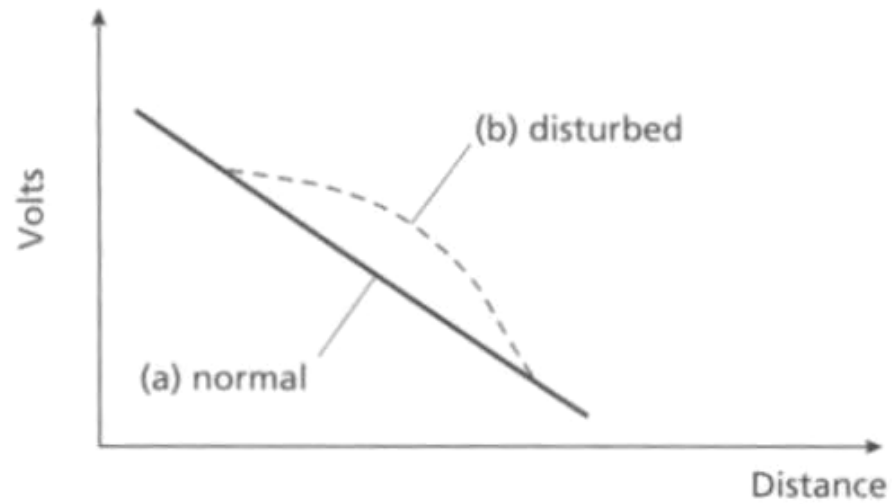
- Twin-coil or slingram systems: dipole source is used

Time-domain EM

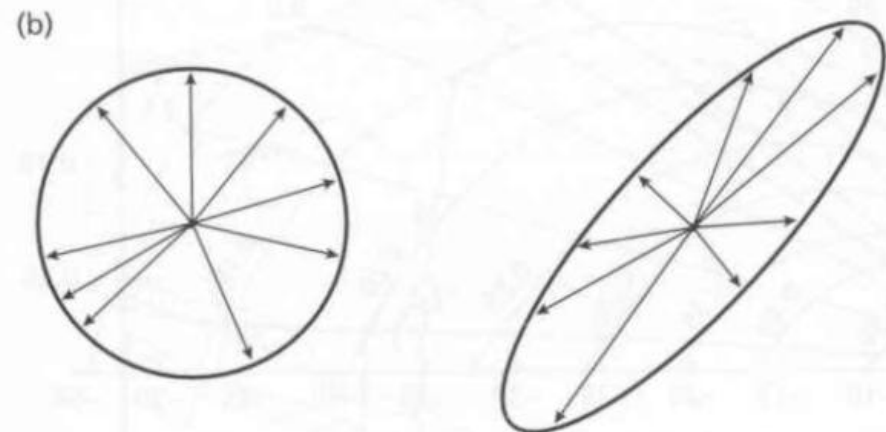
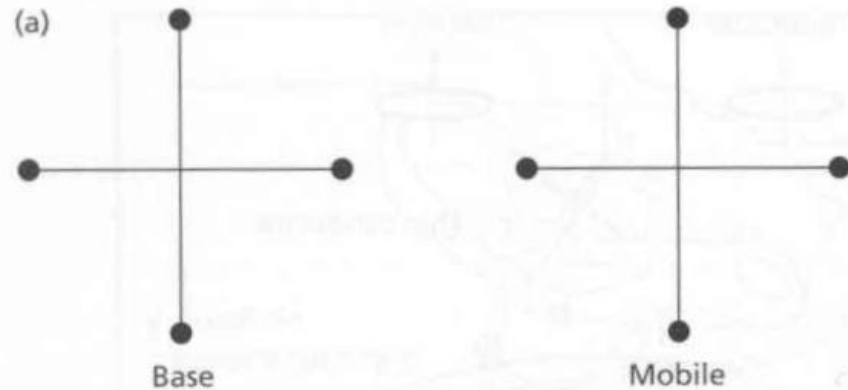
- Transient EM (TEM)

Magnetotelluric (MT)

- The source are fields of **natural origin** (magneto-telluric fields) resulting from flows of charged particles in the **ionosphere**, correlated with diurnal variations in the geomagnetic field caused by solar emissions
- The only electrical technique capable of penetrating to the depths of interest to the oil industry (mapping salt domes and anticlines)
- Frequencies range from 10^{-5} Hz to 20 kHz

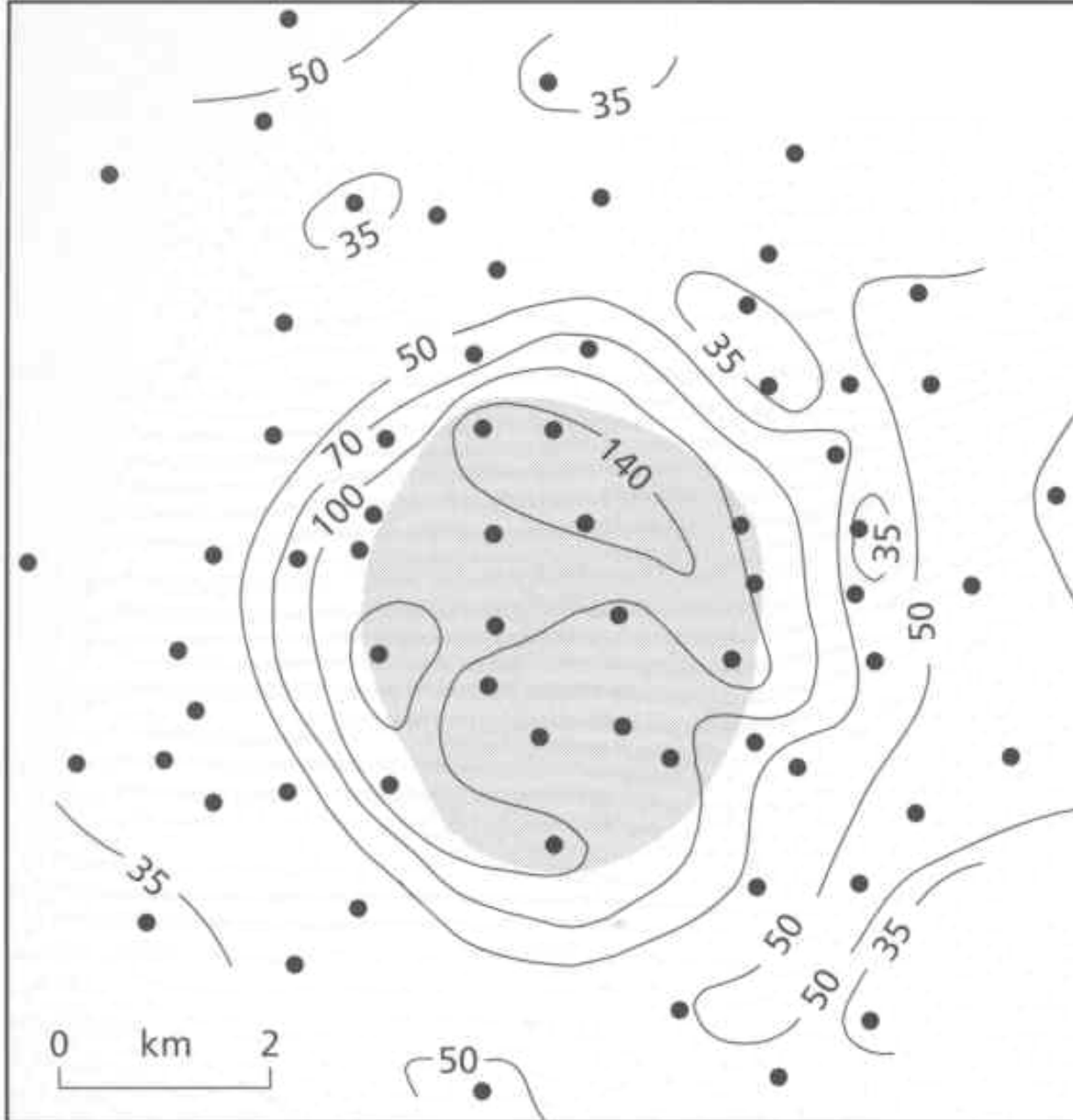


Telluric measurements



unit base circle area (A_1)

measured ellipse area (\hat{A}_2)



Map of A_2/A_1 for a salt dome

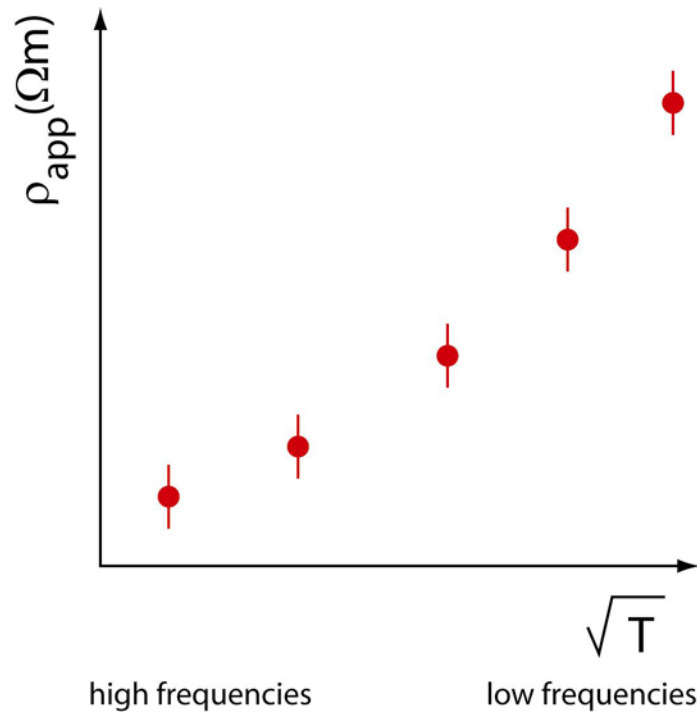


$$\rho_a(\omega) = \frac{1}{\omega\mu_0} |Z(\omega)|^2 = \frac{1}{\omega\mu_0} \left| \frac{E_x(\omega)}{H_y(\omega)} \right|^2$$

Audio-magnetotelluric (AMT)

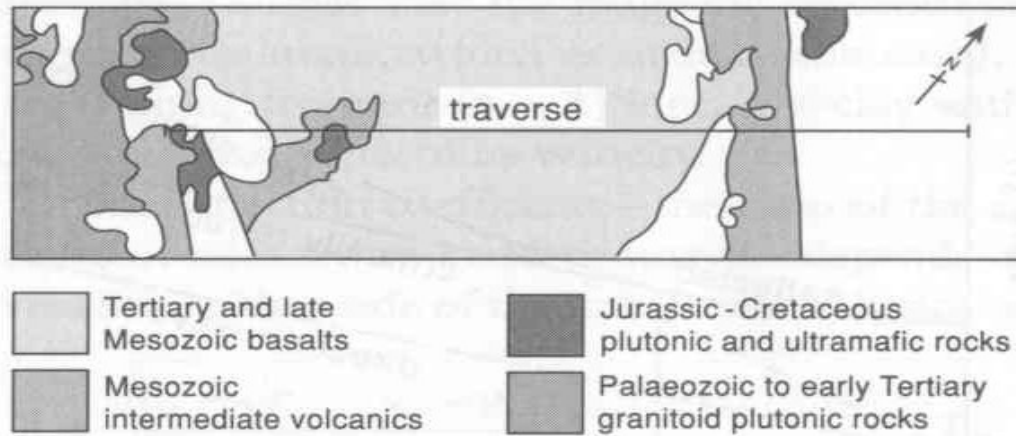
- Use equatorial **thunderstorms as sources** (1 to 20 kHz). These EM fields are called sferics. Sferics propagated around the Earth between the ground and the ionosphere
- The very broad frequency spectrum can be filtered to select a depth of investigation up to 1 km (AMT soundings)
- Method sensitive to noise in urban areas

AMT-MT sounding

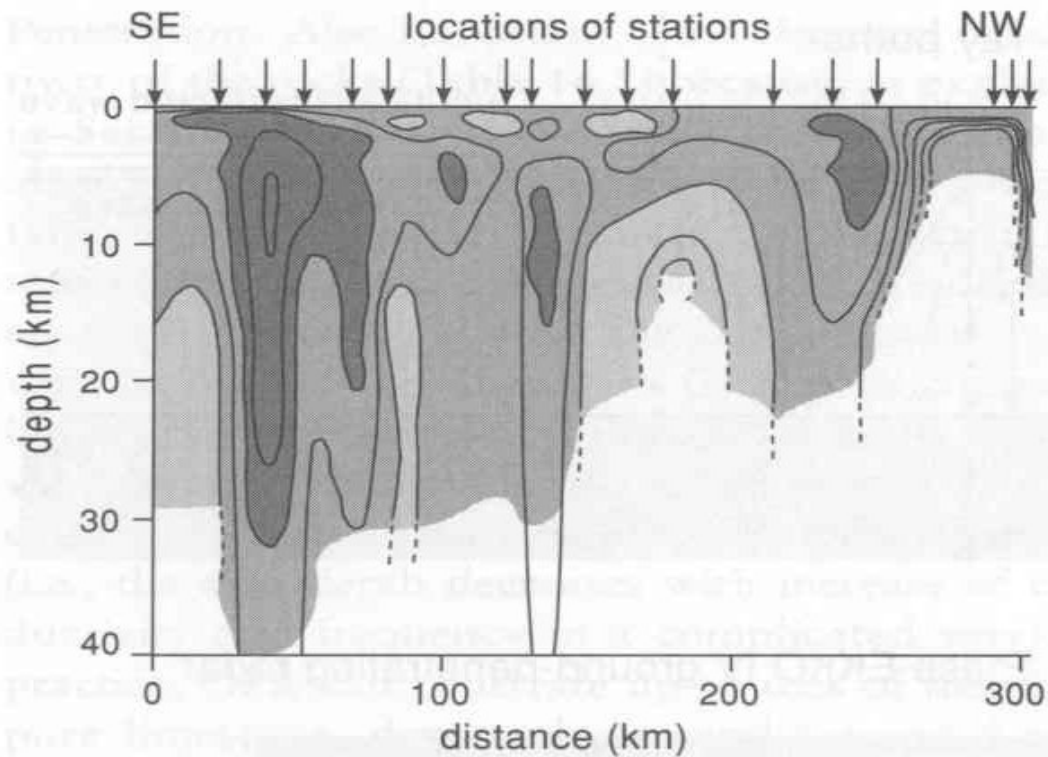


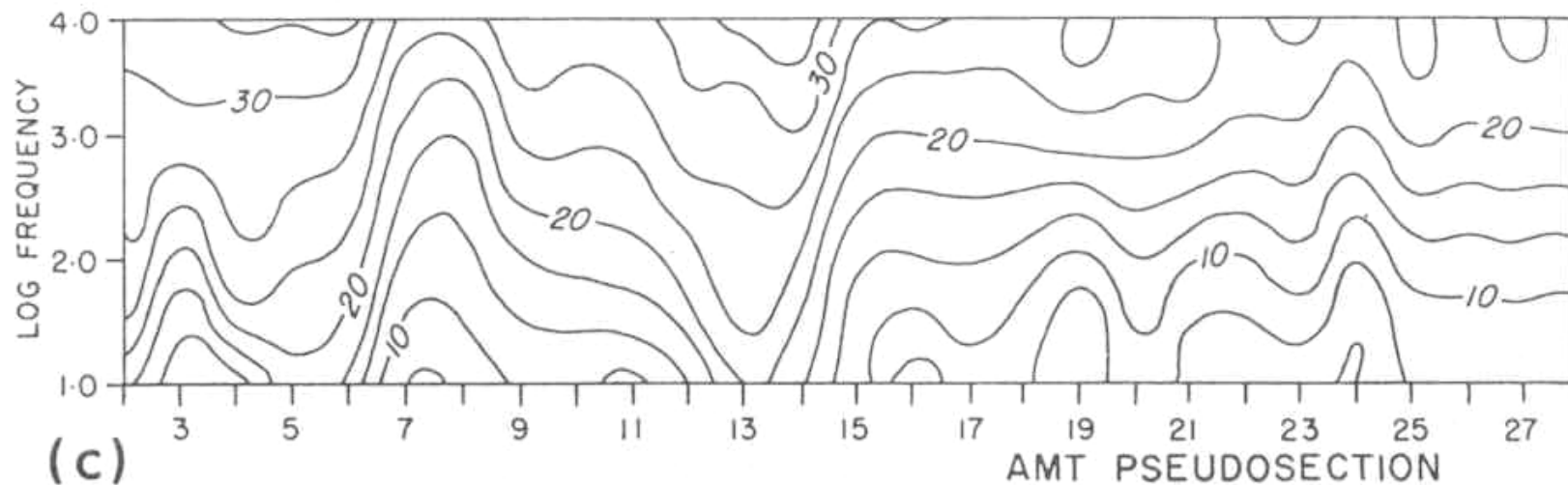
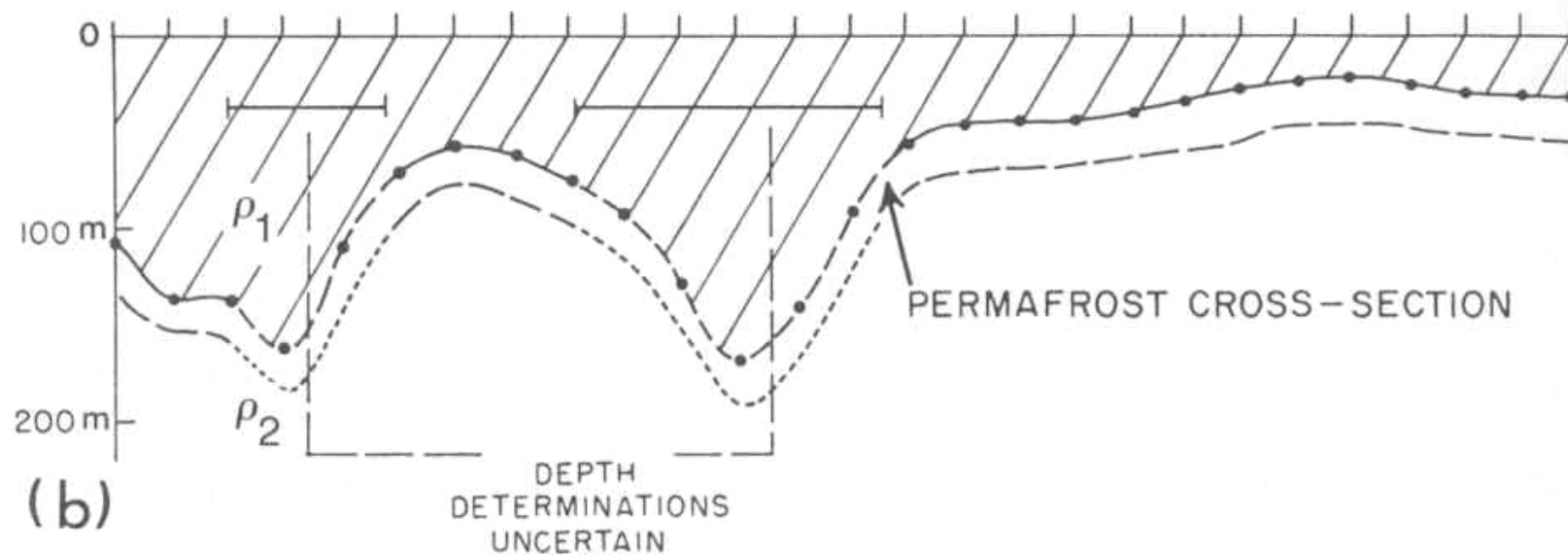
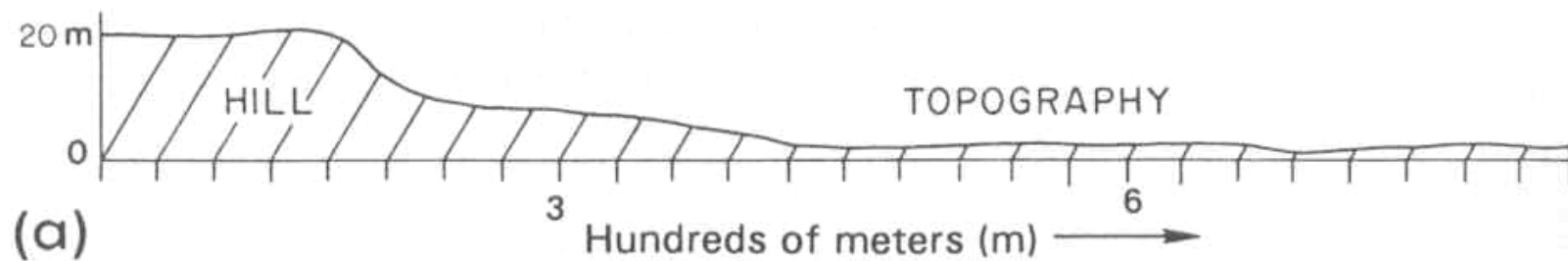
$$\rho_a = \frac{0.2}{f} \left(\frac{E}{H} \right)^2$$

(a) geological map



(b) resistivity section

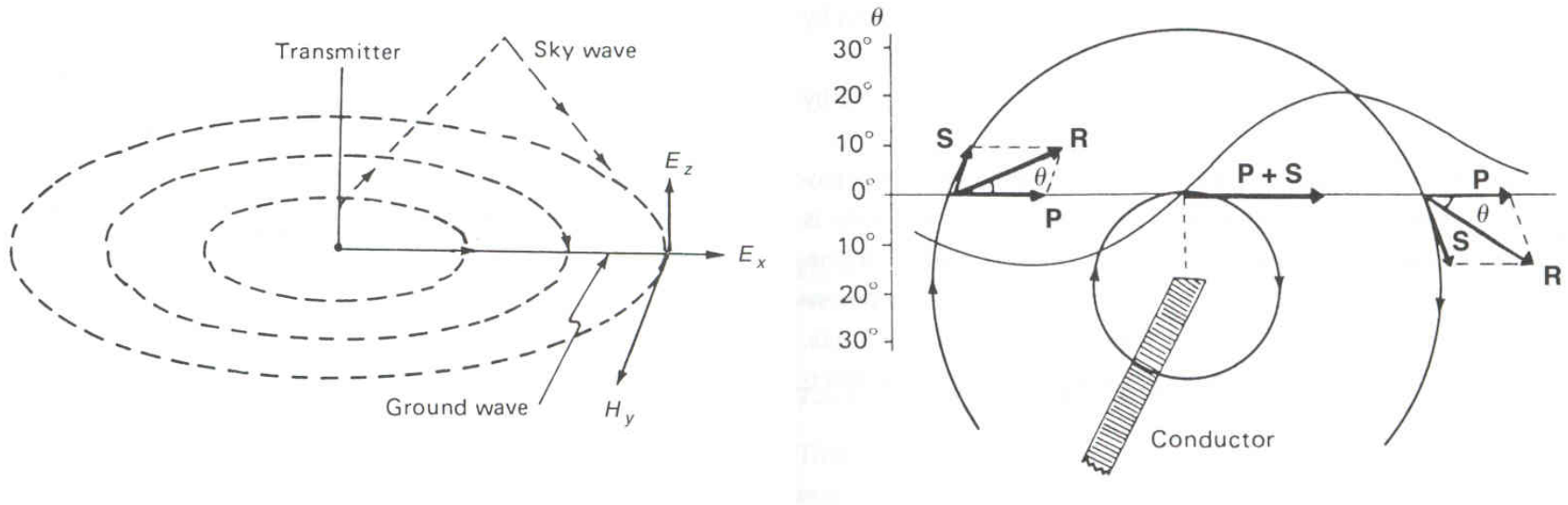




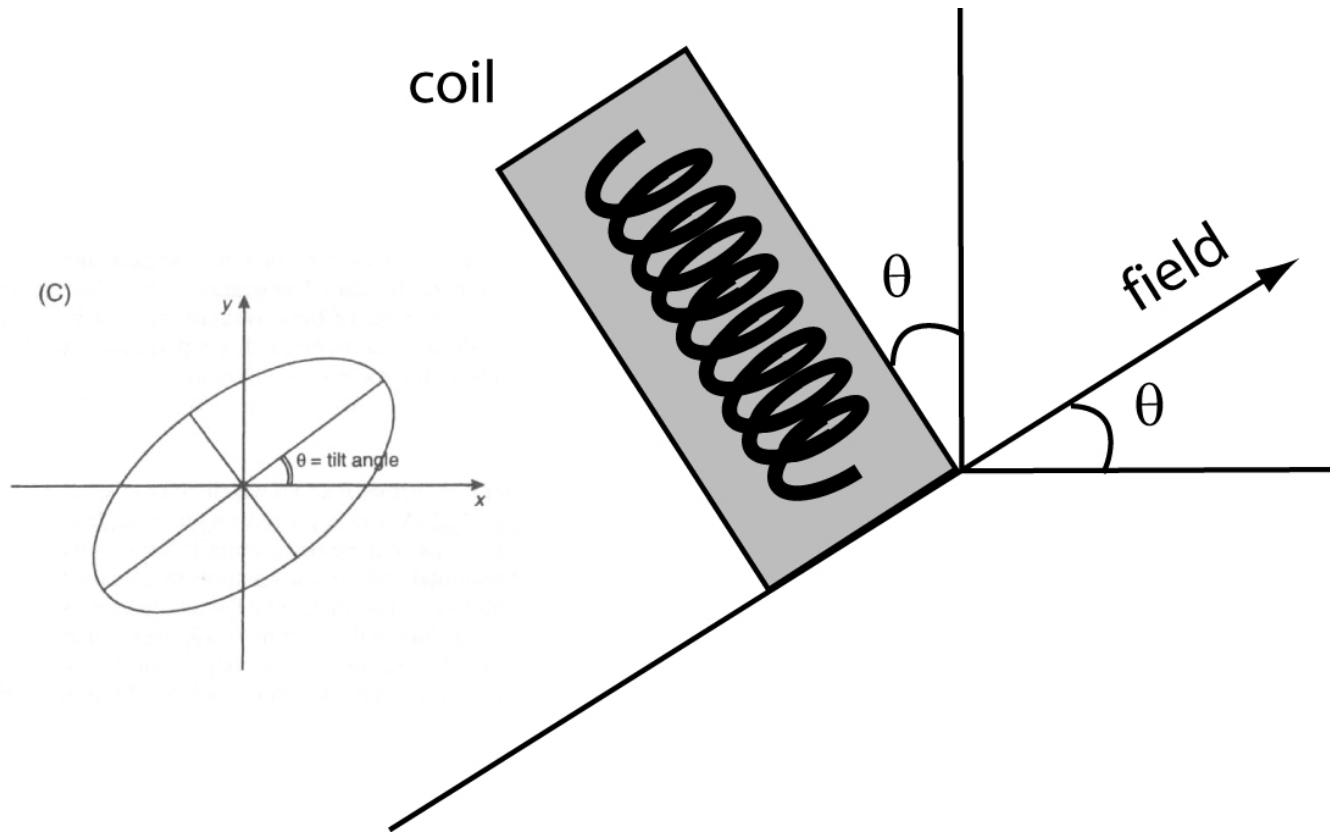
Very-Low Frequency (VLF-tilt)

- Use **submarine communication** waves as sources (10 to 30 kHz). The transmitters are very powerful (>1 MW). The primary EM field is planar and horizontal
- The depth of investigation mainly depends on the conductivity of rocks and the transmitter chosen (from 10m to 100m)
- Disadvantages: transmission frequently broken, difficult to find a transmitter in an appropriate direction
- Advantages: light, fast and easy to use

VFL-tilt measurements



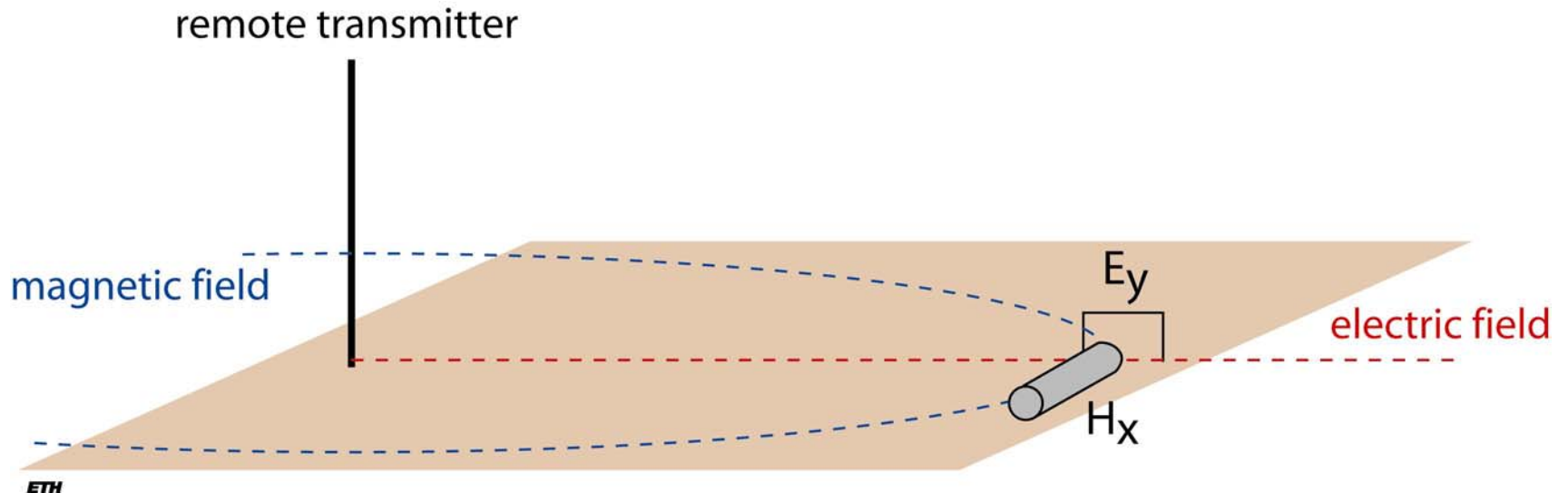
VFL-tilt measurements



Very-Low Frequency (VLF-R)

- Gives apparent resistivity of the ground and phase shift by measuring H and E
- Various **local radio waves** can be used to chose a depth of investigation (frequency can be chosen)

VLF-R measurements

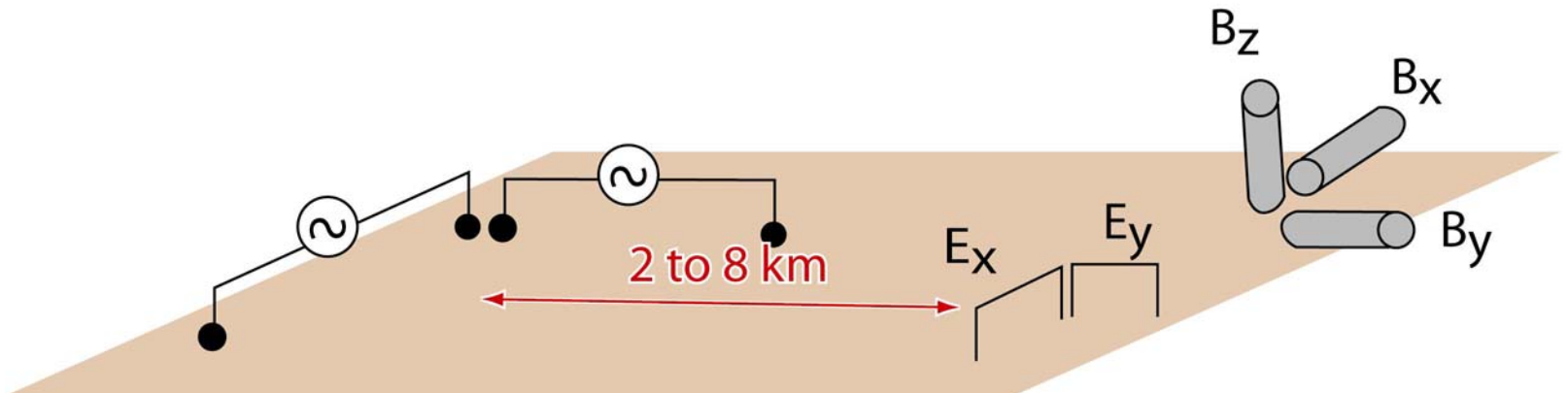
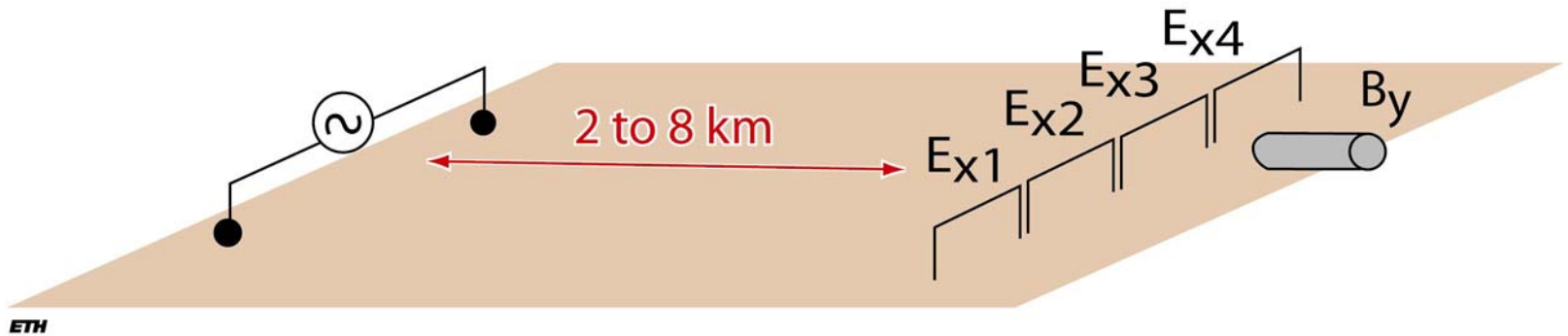


$$\rho_a = \frac{0.2}{f} \left(\frac{E}{H} \right)^2$$

Controlled source AMT (CSAMT)

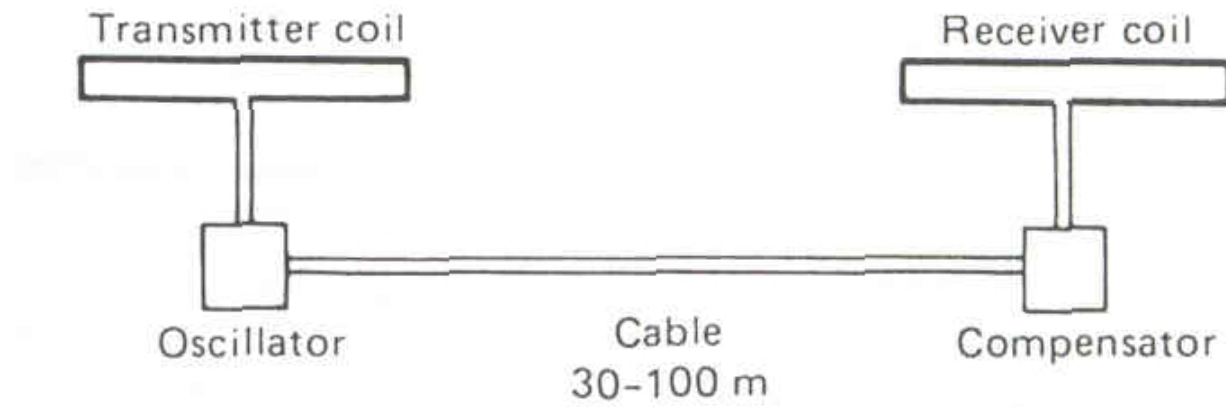
- Similar to MT but using a remote (2 to 8 km) **electrical dipole as source** (1 Hz to 10 kHz)
- The source frequency and location is known

CSAMT measurements



Dipole-source methods

- Measurements tools called twin-coil or slingram systems
- Tx and Rx are **coils** (about 1m diameter) linked by a cable which carries a reference signal in order to compensate the effect of the primary field. By this means, the system subsequently responds only to the secondary fields
- A decomposer split the secondary field into real and imaginary components (display the result as a percentage of the primary field)





EM31 (Geonics), 9.8 kHz, $s=3.66$ m

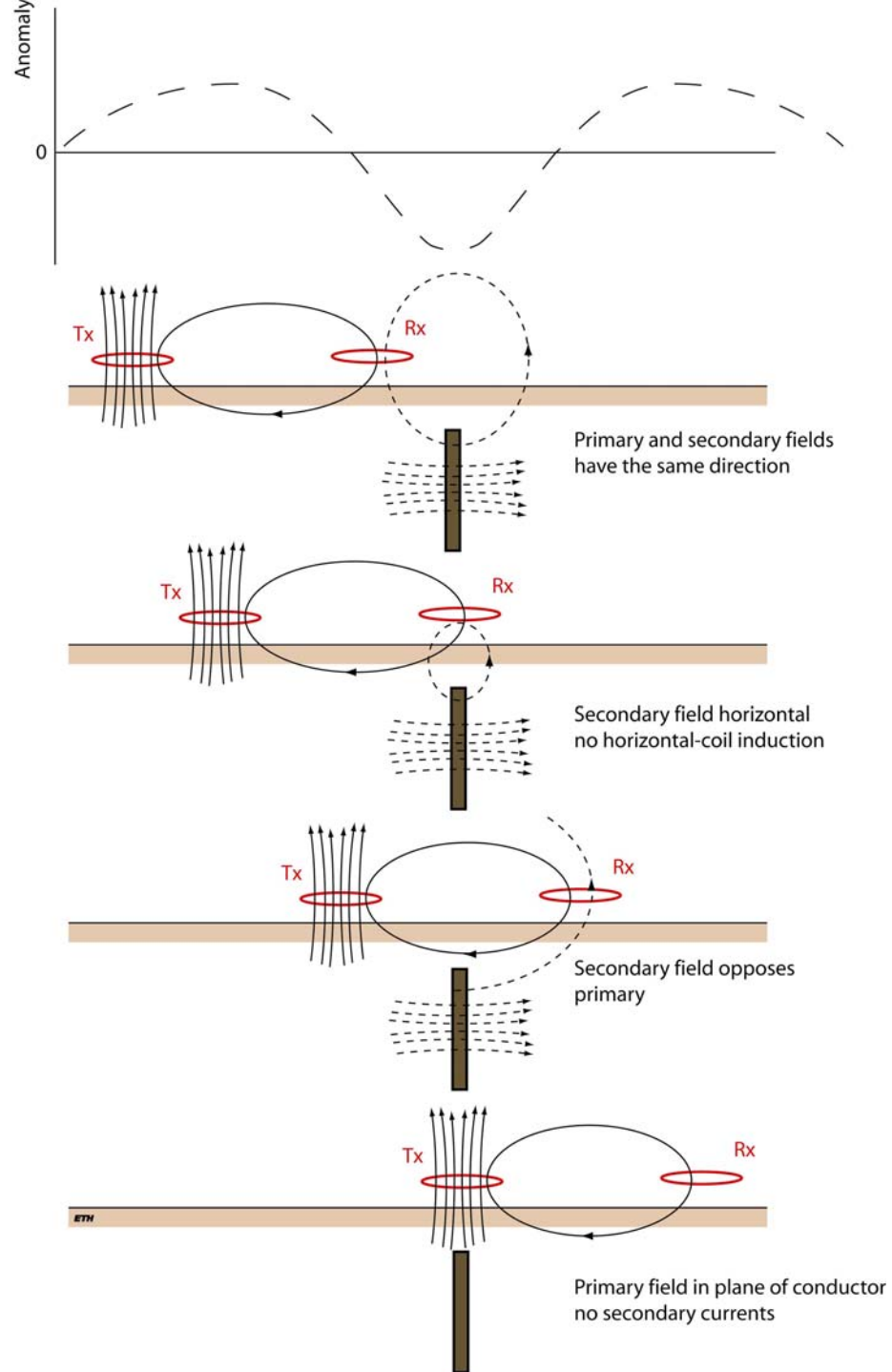


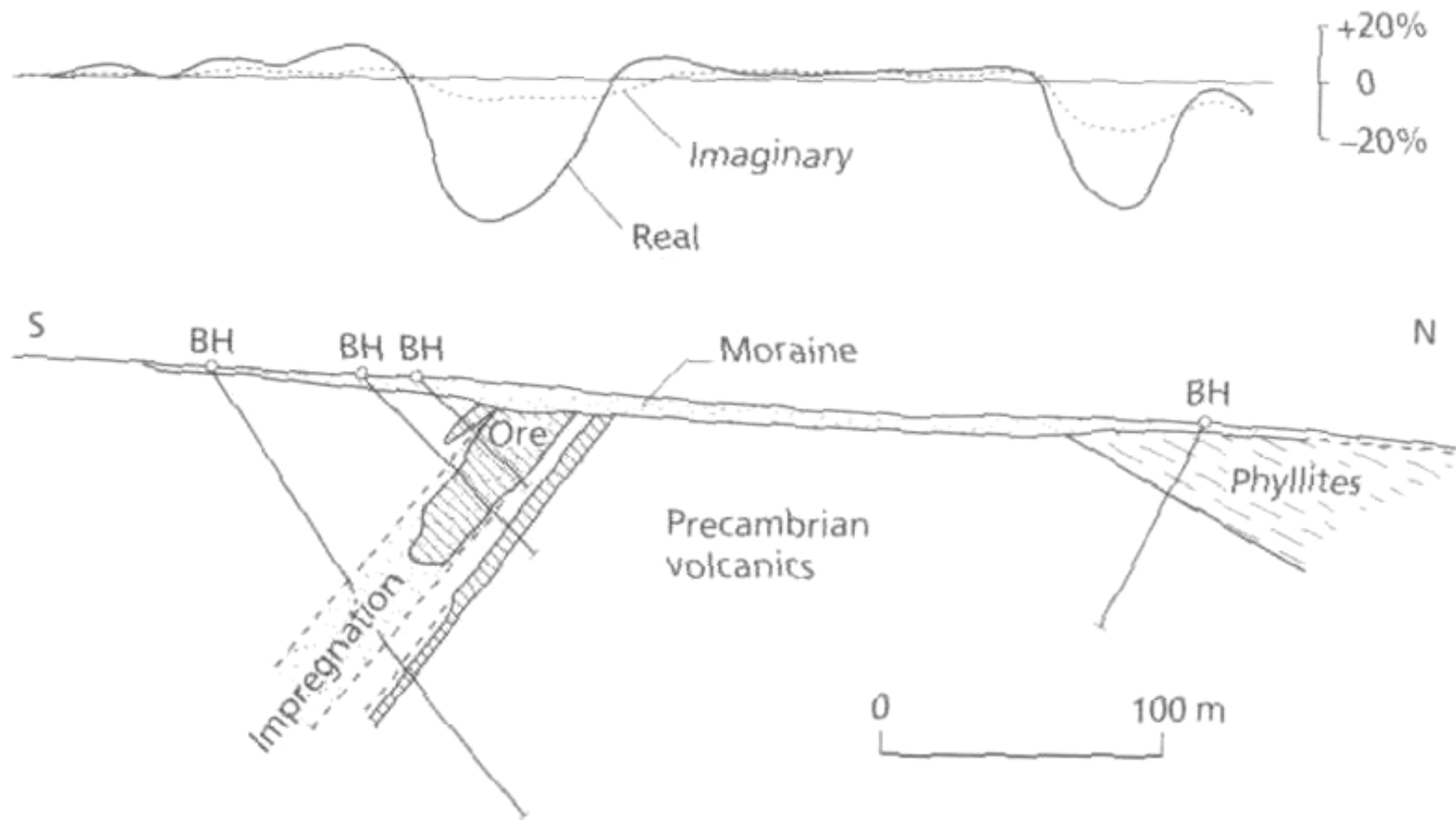
EM34 (Geonics),
 6.4 kHz for $s=10$ m
 1.6 kHz for $s=20$ m
 0.4 kHz for $s=40$ m



EM38 (Geonics), 14.6 kHz, $s=1$ m

s : Rx-Tx distance³⁸





EM at low induction numbers (LIN)

- Depth of investigation depends on the distance Tx-Rx
- The response is proportional to ground conductivity
- Manufacturer adapts the Rx-Tx distance (s) and frequency (f) for a **LIN** approximation, i.e. $s \ll \delta$:

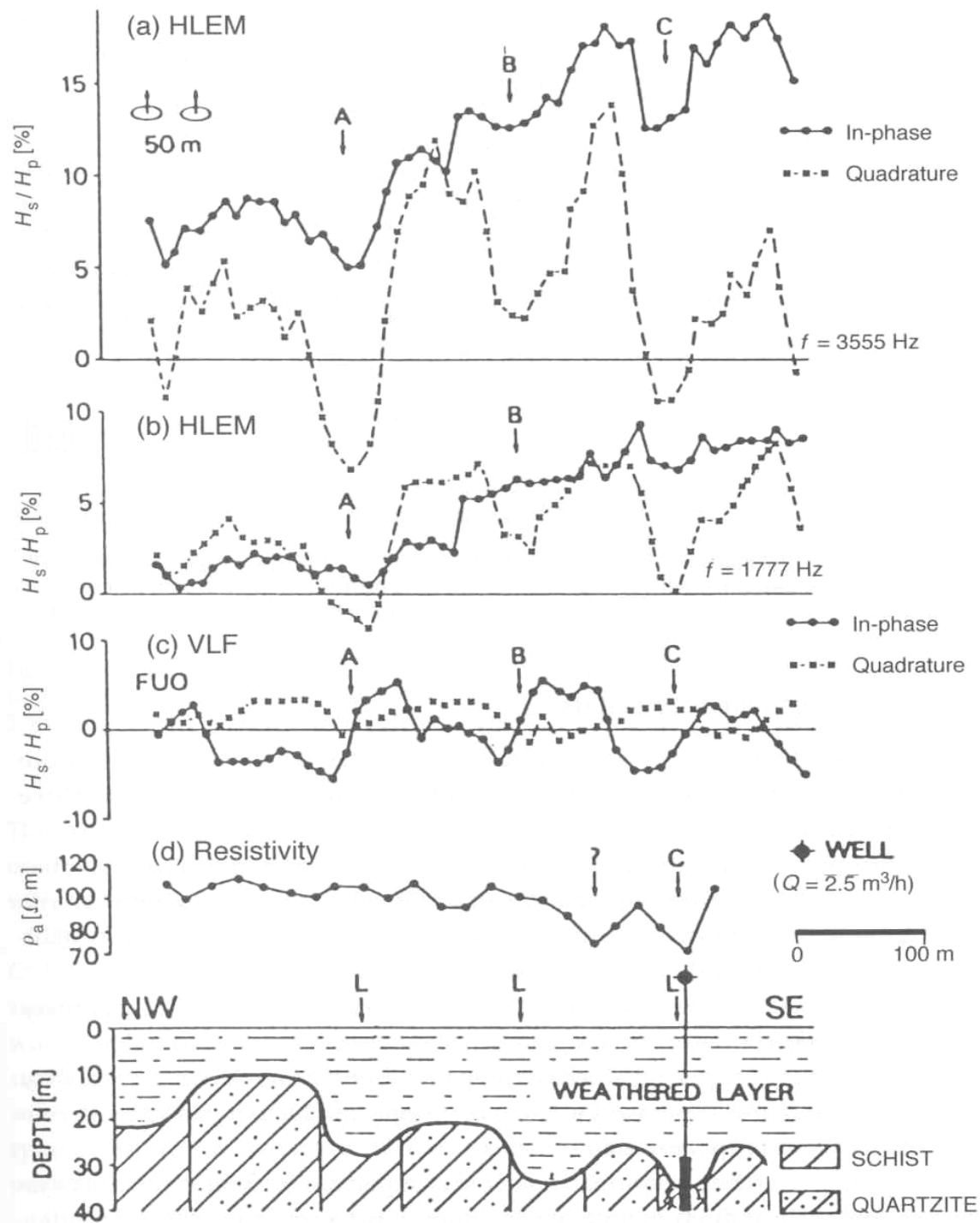
$$N_B \ll 1 \Rightarrow \frac{H_S}{H_P} \frac{4}{i\mu_0 \omega \sigma s^2} \cong \sigma_a$$

$N_B = s / \delta$ is the induction number

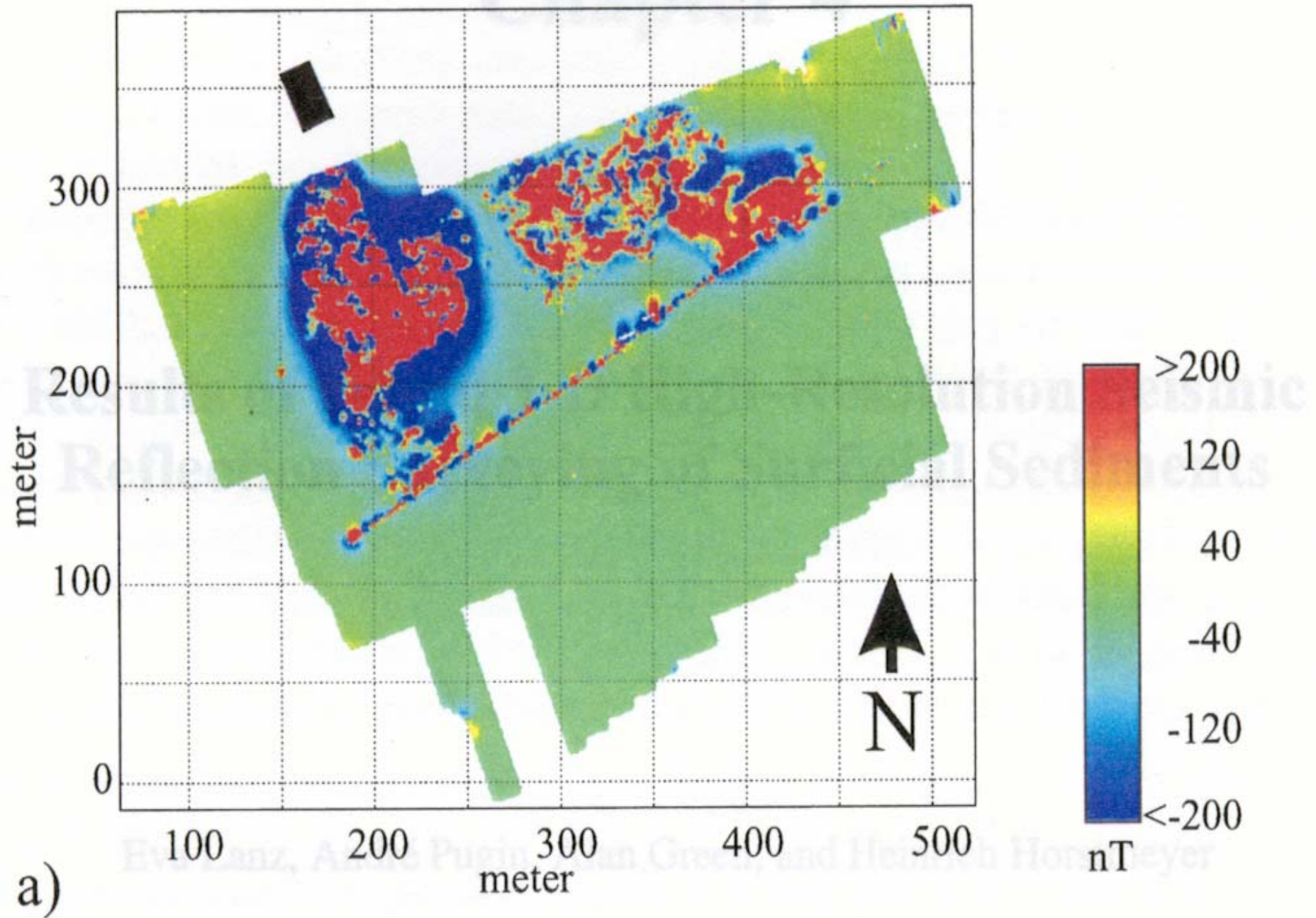
$$\delta \cong 503 \sqrt{\frac{\rho}{f}}$$

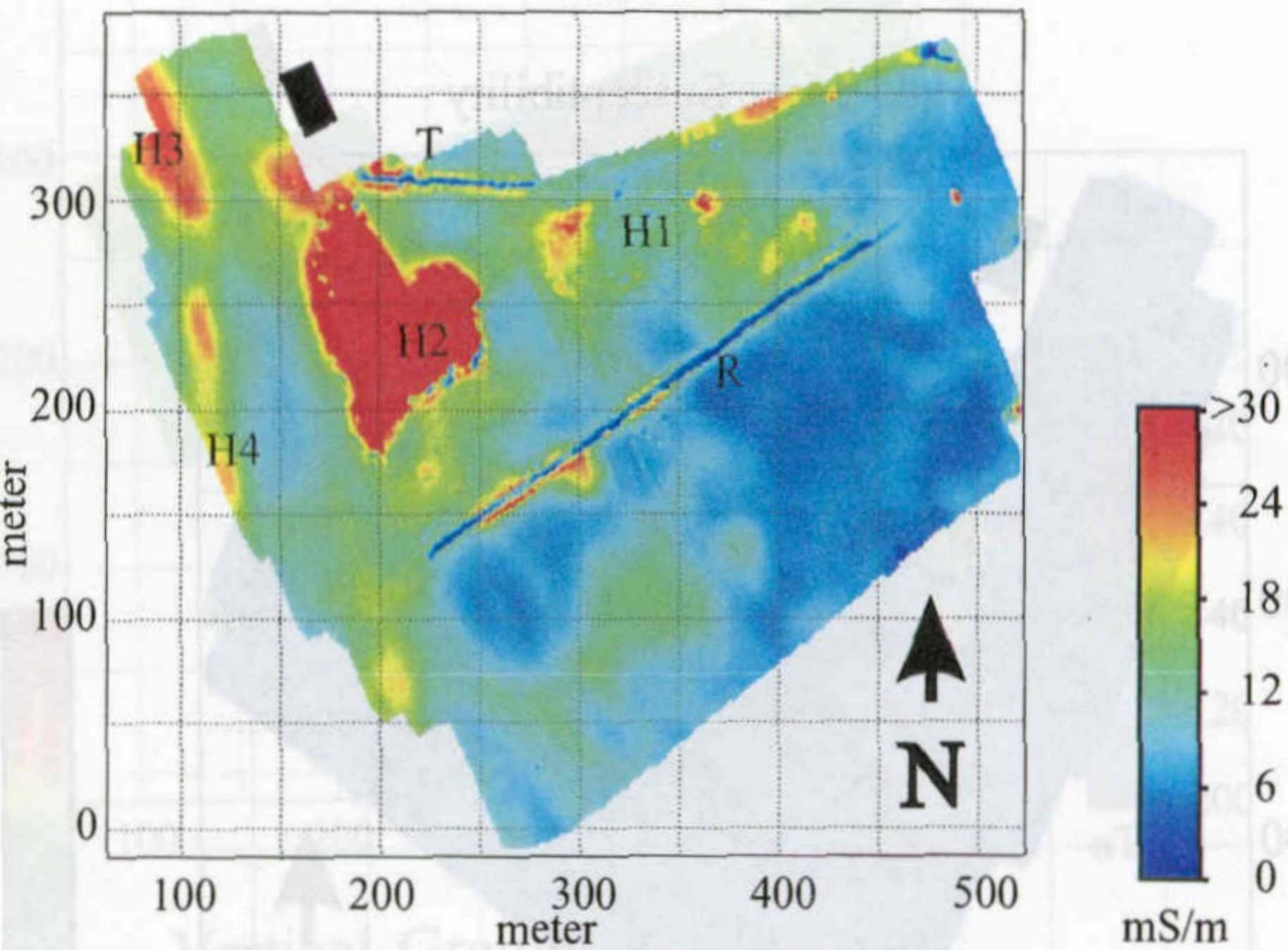
CST and VES using LIN

- CST: moving vertical and horizontal dipoles with various **constant depth** (survey principle similar to resistivity CST and tomography)
- VES: **increasing Tx-Rx spacing** around a same location point and using vertical and horizontal dipoles (survey principle similar to resistivity VES)



Bottom Sensor Total-Field Magnetic

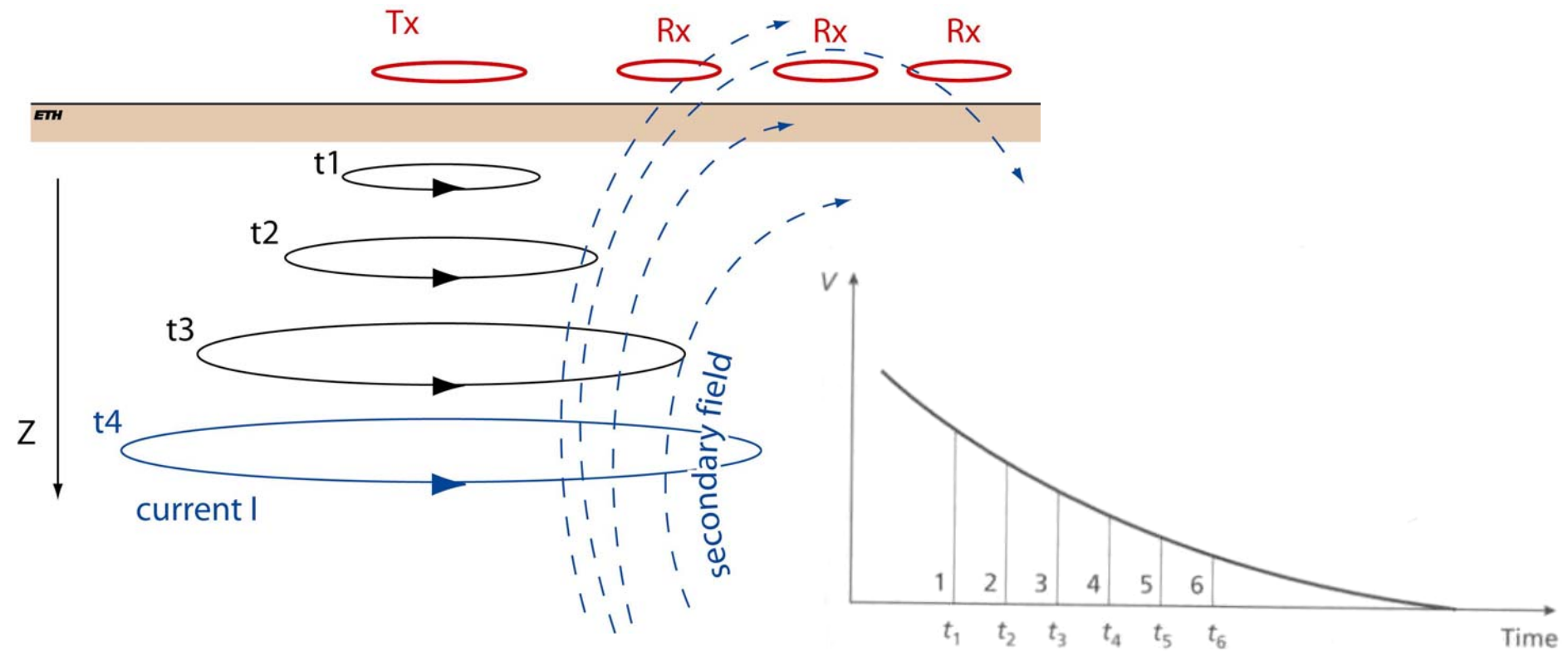




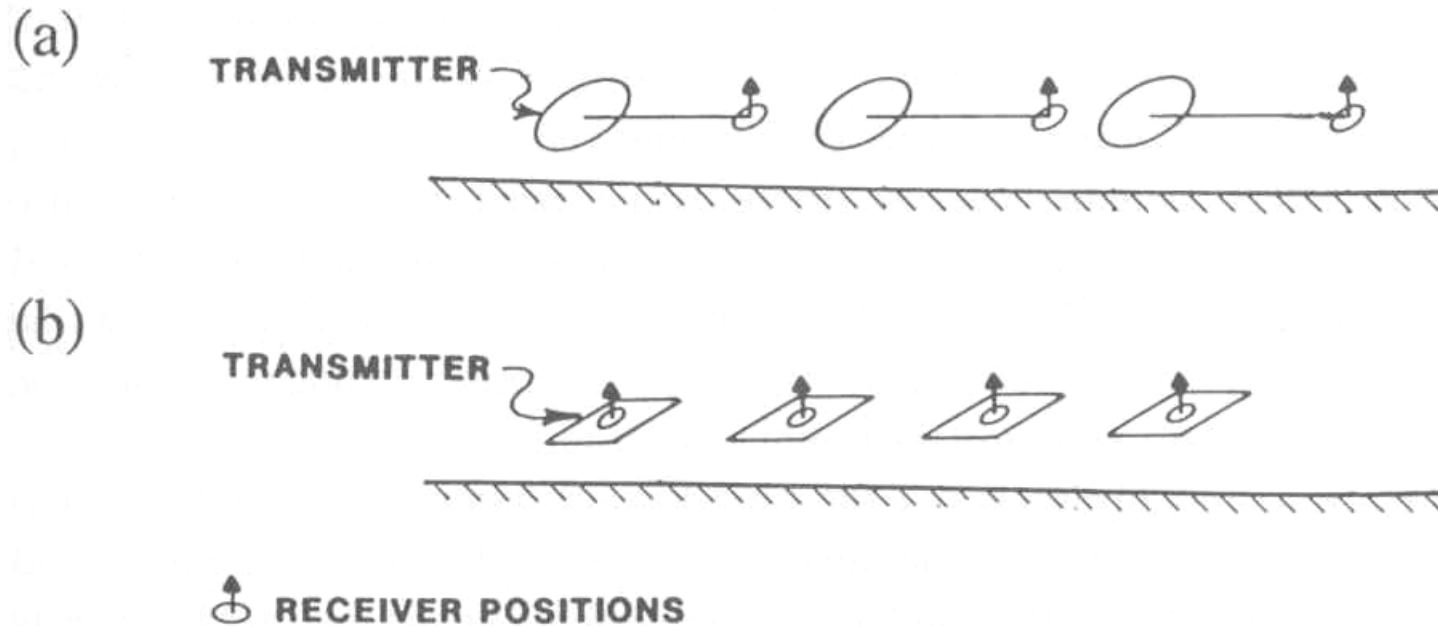
Transient EM (TEM)

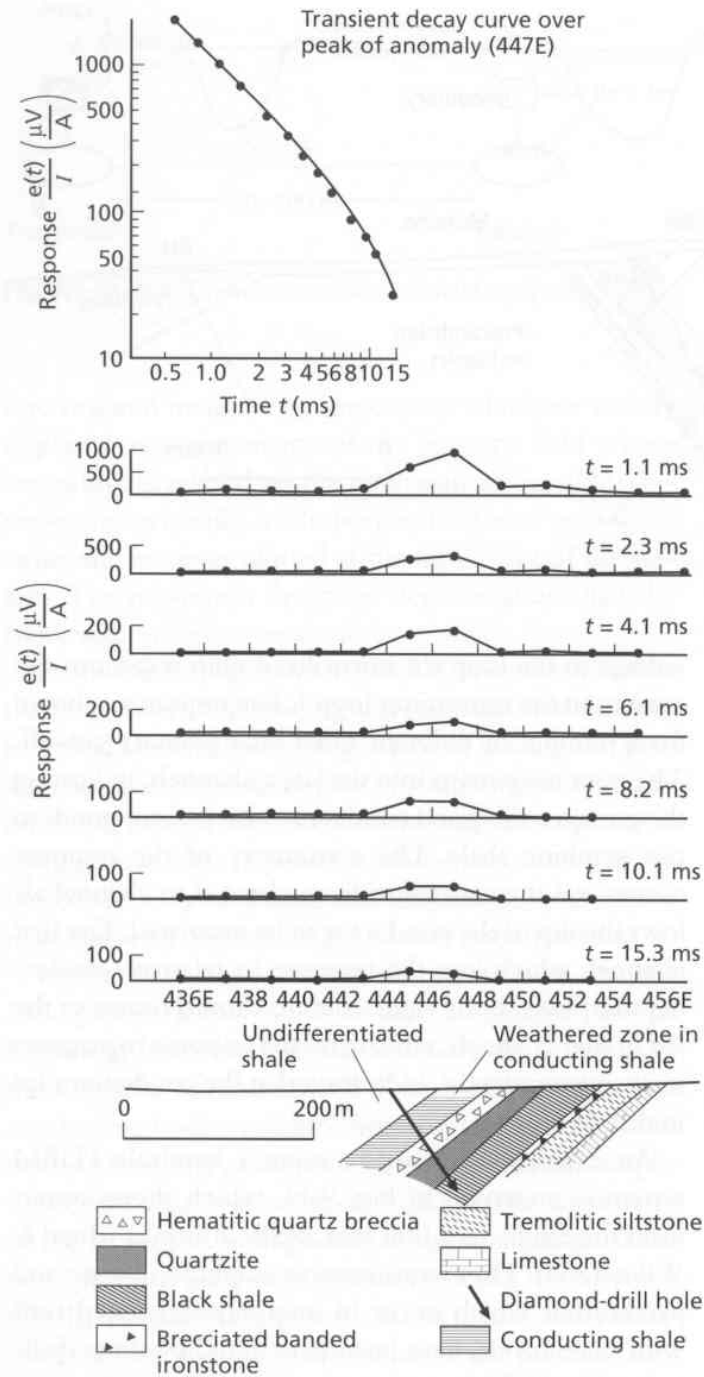
- TEM uses a primary field which is not continuous but consists of a **series of pulses** separated by measurement periods when the transmitter is inactive
- Primary and secondary fields are clearly separated
- Investigation depth up to several km could be achieved, but difficult to use in shallow geophysics (no reliable information in the 0-10 m depth range)

TEM measurements

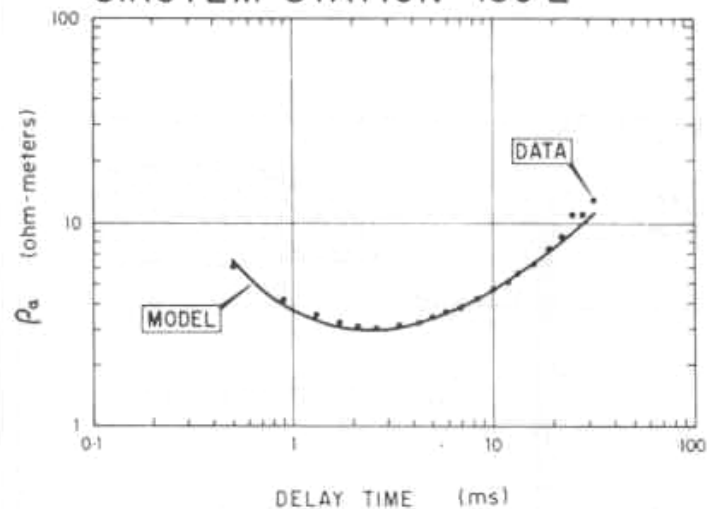


TEM measurements





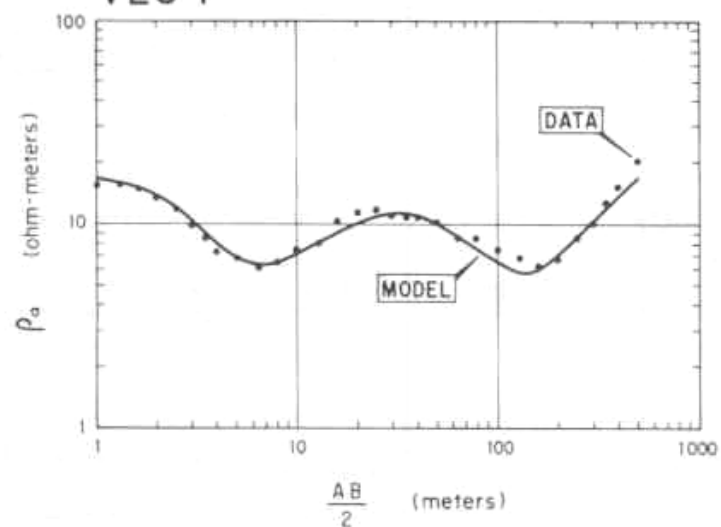
SIROTEM STATION 150 E



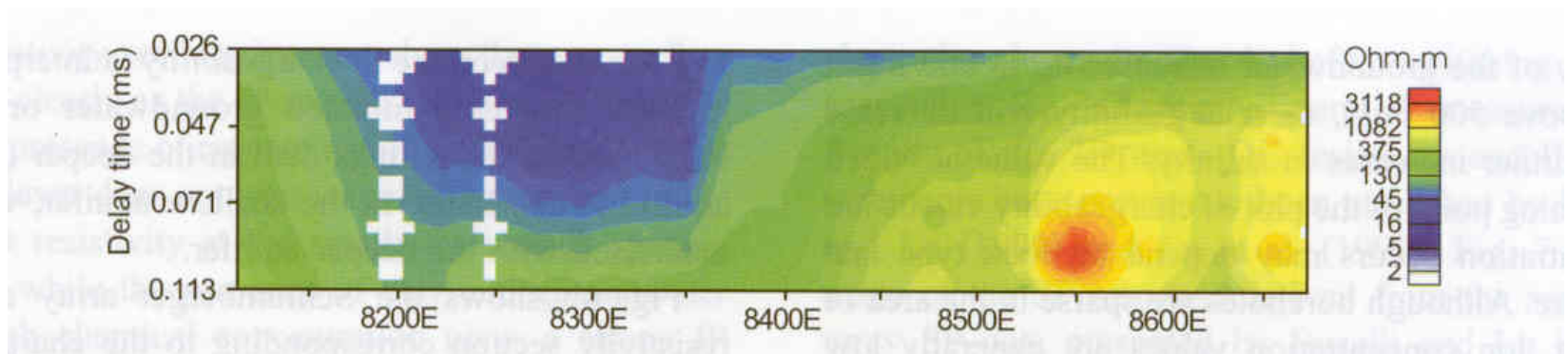
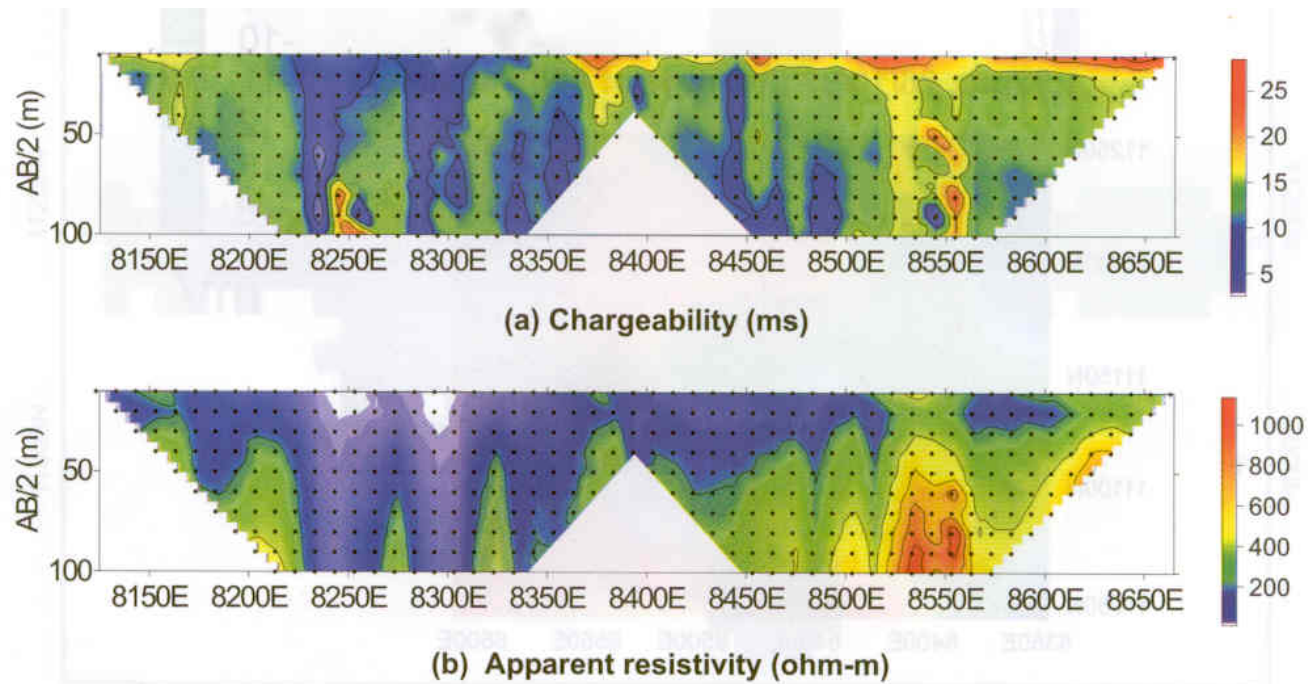
LAYER	THICKNESS (meters)	RESISTIVITY (ohm-meters)
1	1.5 *	17 *
2	3.0 *	3.1 *
3	24 **	21
4	36 **	1.4 **
5		380

- * Fixed parameter
- ** Influential parameter

VES 1



LAYER	THICKNESS (meters)	RESISTIVITY (ohm-meters)
1	1.5	17
2	3.0	3.1
3	20.0	22.0
4	43.0	1.6
5		250.0



Remarks on interpretation

- Indirect approach using theoretical computations of simple geometry shapes (spheres, cylinders, thin sheets, horizontal layers)
- Laboratory modeling (using special scaling rules)
- Use of master curves for simple Earth structures
- Mainly qualitative. Quantitative inversion in development, soundings very used



3. Conclusions

Advantages

- Surveys are easy to carry out, non-expensive (require less field operators than resistivity methods)
- Rapid qualitative overview
- No galvanic coupling with the ground required
- Theoretically less sensitive to non-unicity in the solution than resistivity

Drawbacks

- Quantitative interpretation of EM anomalies is complex
- Penetration not very great if very conductive superficial layers are present